EFX24-SR - Damper Actuator













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| Technical Data | |
| Power Supply | 24 VAC±20%, 50/60Hz, 24 VDC+20%/-10% |
| Power Consumption Running | 8 W |
| Power Consumption Holding | 4.5 W |
| Transformer Sizing | 14 VA (class 2 power source) |
| Shaft Diameter | 1/2" to 1.05" round, centers on 3/4" with |
| | insert, 1.05" without insert |
| Electrical Connection | 3 ft [1m], 10 ft [3m] or 16 ft [5m] 18 GA |
| | appliance or plenum cables, with or without 1/2" conduit connector |
| Overload Protection | electronic throughout 0° to 95° rotation |
| Electrical Protection | actuators are double insulated |
| Operating Range Y | 2 to 10 VDC, 4 to 20 mA w/ ZG-R01 (500 Ω, |
| oporating range i | 1/4 W resistor) |
| Input Impedance | 100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for |
| | 4 to 20 mA |
| Feedback Output U | 2 to 10 VDC, 0.5 mA max |
| Angle of Rotation | max. 95° (adjustable with mechanical end |
| | stop, 35° to 95°) |
| Torque | 270 in-lbs [30 Nm] minimum |
| Direction of Rotation (Motor) | reversible with built-in switch |
| Direction of Rotation (Fail-Safe) | reversible with CW/CCW mounting |
| Position Indication | visual indicator, 0° to 95° (0° is full spring |
| Manual Override | return position) 5 mm hex crank (3/16" Allen), supplied |
| | 95 sec |
| Running Time (Motor) Running Time (Fail-Safe) | 95 Sec <20 sec @ -4°F to 122°F [-20°C to 50°C], < |
| Rullling Time (Fall-Sale) | <20 Sec @ -4 F to 122 F [-20 C to 50 C], < 60 sec @ -22 F [-30 C] |
| Humidity | max. 95% RH non-condensing |
| Ambient Temperature Range | -22°F to +122°F [-30°C to +50°C] |
| Storage Temperature Range | -40°F to +176°F [-40°C to +80°C] |
| Housing | NEMA 2, IP54, UL enclosure type 2 |
| Housing Material | Aluminum die cast and plastic casing |
| Agency Listings† | cULus acc. to UL60730-1A/-2-14, CAN/CSA |
| 3 -7 - 9-1 | E60730-1:02, CE acc. to 2004/108/EC |
| Noise Level (Motor) | ≤56.5 dB (A) |
| Noise Level (Fail-Safe) | ≤71 dB (A) |
| Servicing | maintenance free |
| Quality Standard | ISO 9001 |
| Weight | 9.8 lb [4.4 kg] |
| | |

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 3

Torque min. 270 in-lb, for control of air dampers

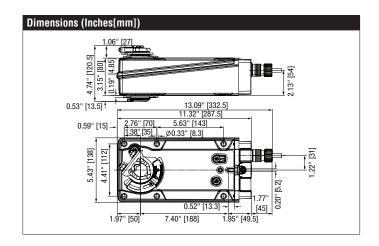
Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05" in diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The actuator operates in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. A 2 to 10 VDC feedback signal is provided for position indication. Not to be used for a master-slave application.

Operation

The EF..24-SR series actuators provide true spring return operation for reliable failsafe application and positive close off on air tight dampers. The spring return system provides constant torque to the damper with, and without, power applied to the actuator. The EF..24-SR series provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The EF..24-SR uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact fail-safe position. The ASIC monitors and controls the brushless DC motor's rotation and provides a digital rotation sensing function to prevent damage to the actuator in a stall condition. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The EF..24-SR actuator is shipped at +5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

Installation Note: Use flexible metal conduit. Push the UL listed conduit fitting device over the actuator's cable to butt against the enclosure. Screw in conduit connector. Jacket the actuator's input wiring with UL listed flexible conduit. Properly terminate the conduit in a suitable junction box.



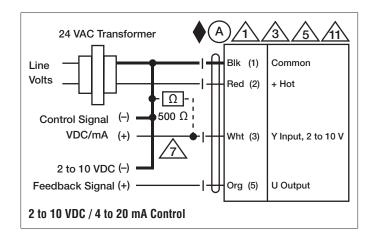
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Modulating, Spring Return, 24 VAC/DC, for 2 to 10 VDC or 4 to 20 mA Control Signal

| Accessorie | 39 |
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| AV8-25 | 9.8" shaft extension for 5/16" to 1" diameter shafts. |
| EF-P | Anti-rotation bracket EFB(X)/GKB(X)/GMB(X). |
| IND-EFB | EFB(X) position indicator. |
| K9-2 | Standard EFB(X) clamp (1/2" to 1.05"). |
| KG10A | Ball joint for 3/8" diameter rod, zinc plated. |
| KH10 | Univ. crankarm, slot 21/64" w, for 9/16" to 1" dia. shafts. |
| KH-EFB | EFB(X) crankarm (with 1.05" diameter shaft pass through). |
| SH10 | Push rod for KG10A ball joint (36" L, 3/8" diameter). |
| T00L-07 | 13 mm wrench. |
| ZG-100 | Univ. right angle bracket (17" H x 11-1/8" W x 6" base). |
| ZG-120 | Jackshaft mounting bracket. |
| ZG-DC1 | Damper clip for damper blade, 3.5" width. |
| ZG-DC2 | Damper clip for damper blade, 6" width. |
| ZG-EFB | EFB(X) crankarm adaptor kit. |
| ZG-JSA-3 | 1.05" diameter jackshaft adaptor (12" L). |
| ADS-100 | Analog to digital switch for modulating actuators. |
| IRM-100 | Input rescaling module for modulating actuators. |
| PS-100 | Actuator power supply and control simulator. |
| PTA-250 | Pulse width modulation interface for modulating actuators. |
| SGA24 | Positioner control for modualting actuators (surface mount). |
| SGF24 | Positioner control for modulating actuators (flush mount). |
| TF-CC US | Cable conduit connector, 1/2". |
| ZG-R01 | 4 to 20 mA adaptor, 500Ω , $1/4$ W resistor w 6" pigtail wires. |
| ZG-R02 | 50% voltage divider kit (resistors with wires). |
| ZG-SGF | Mounting plate for SGF. |
| ZG-X40 | 120 to 24 VAC, 40 VA transformer. |

Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.



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Wiring Diagrams



WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Meets cULus requirements without the need of an electrical ground connection.



Actuators with appliance cables are numbered.



Provide overload protection and disconnect as required.



Actuators may also be powered by 24 VDC.



Only connect common to negative (-) leg of control circuits.



A 500 Ω resistor (ZG-R01) converts the 4 to 20 mA control signal to 2



Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.