LF24-MFT US - Damper Actuator

Modulating, Spring Return, 24 V, Multi-Function Technology®











	REG. EQUIP.
Technical Data	
Power Supply	24 VAC, ±20%, 50/60 Hz, 24 VDC, ±10%
Power Consumption Running	2.5 W
Power Consumption Holding	1 W
Transformer Sizing	5 VA (class 2 power source)
Shaft Diameter	3/8" to 1/2" round, centers on 1/2"
Electrical Connection	3ft [1m], 18 GA appliance cable with 1/2" conduit connector
Overload Protection	electronic throughout 0° to 95° rotation
Electrical Protection	actuators are double insulated
Operating Range Y	2 to 10 VDC, 4 to 20 mA w/ ZG-R01 (500 Ω , 1/4 W resistor), variable (VDC, PWM, floating point, on/off)
Input Impedance	$100~k~\Omega$ for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA, 1500 Ω for PWM, floating point and 0n/Off
Feedback Output U	2 to 10 VDC, 0.5 mA max, VDC variable
Angle of Rotation	Max. 95°, adjustable with mechanical stop
Torque motor	Min. 35 in-lbs [4 Nm]
Direction of Rotation (Motor)	reversible with built-in switch
Direction of Rotation (Fail-Safe)	reversible with CW/CCW mounting
Position Indication	visual indicator, 0° to 95° (0° is full spring
	return position)
Running Time (Motor)	150 sec
Running Time (Fail-Safe)	<25 sec @ -4°F to 122°F [-20°C to 50°C], <60 sec @ -22°F [-30°C]
Angle of Rotation Adaptation	off (default)
Override Control	min. position = 0%, mid. Position = 50%, max. position = 100% (Default)
Ambient Humidity	max. 95% RH non-condensing
Ambient Temperature Range	-22°F to 122°F [-30°C to 50°C]
Storage Temperature Range	-40°F to 176°F [-40°C to 80°C]
Housing	NEMA 2, IP54
Housing Material	zinc coated steel
Agency Listings†	cULus acc. To UL 873 and CAN/CSA C22.2 No. 24-93
Noise Level (Motor)	<30 dB (A)
Noise Level (Fail-Safe)	<62 dB (A)
Servicing	maintenance free
Quality Standard	ISO 9001
Weight	3.3 lb [1.5 kg]

^{*}Variable when configured with MFT options.

†Rated Impulse Voltage 800V, Type of action 1.AA, Control Pollution Degree 3

Torque min. 35 in-lb, Control 2 to 10 VDC (DEFAULT), Feedback 2 to 10 VDC (DEFAULT)

Application

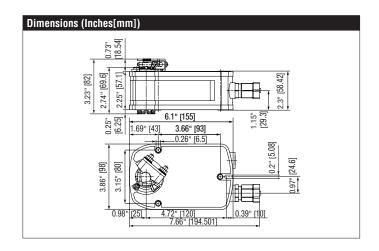
For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication.

Default/Configuration

Default parameters for 2 to 10 VDC applications of the LF.-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Operation

The LF24-MFT US actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the damper or valves mechanical stop and use this point for its zero position during normal control operations. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuator's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The LF24-MFT US is mounted directly to control shafts up to 3/4" diameter (K6-1 clamp) and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The LF24-MFT US actuator is shipped in the zero position, compression against seats or gaskets for tight shut-off is accomplished manually.

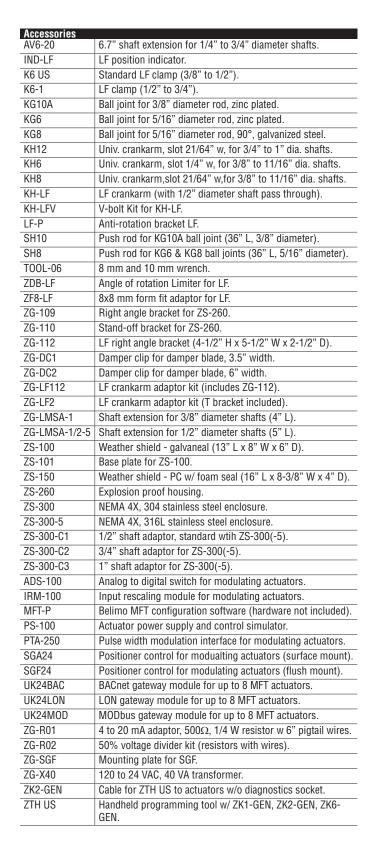


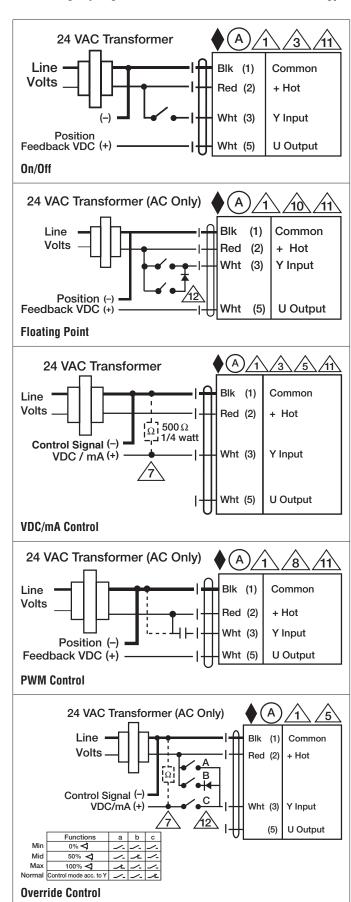




LF24-MFT US - Damper Actuator

Modulating, Spring Return, 24 V, Multi-Function Technology®





LF24-MFT US - Damper Actuator

Modulating, Spring Return, 24 V, Multi-Function Technology®



Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a shaft up to a 3/4" diameter and center on a 1/2" shaft (default). Actuator shall deliver a minimum output torque of 35 in-lbs. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators with auxiliary switches must be constructed to meet the requirements for Double Insulation so an electrical ground is not required to meet agency listings. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Wiring Diagrams



WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.



Meets cULus requirements without the need of an electrical ground connection.



Actuators with appliance cables are numbered.



Provide overload protection and disconnect as required.



Actuators may also be powered by 24 VDC.



Only connect common to negative (-) leg of control circuits.



A 500 Ω resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.



Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 VAC line.



For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.



Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.



IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).