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Technical Data

| Power Supply | 24 VAC, $\pm 20 \%, 50 / 60 \mathrm{~Hz}, 24 \mathrm{VDC}, \pm 10 \%$ |
| :---: | :---: |
| Power Consumption Running | 3.5 W |
| Power Consumption Holding | 1.25 W |
| Transformer Sizing | 5.5 VA (class 2 power source) |
| Shaft Diameter | $1 / 2^{\prime \prime}$ to 1.05 " round, centers on $1 / 2^{\prime \prime}$ and $3 / 4$ " with insert, 1.05 " without insert |
| Electrical Connection | 18 GA plenum rated cable with $1 / 2^{\prime \prime}$ conduit connector protected NEMA 2 (IP54) 3ft [1m] 10ft [ 3 m ] and 16 ft [ 5 m ] |
| Overload Protection | electronic throughout $0^{\circ}$ to $95^{\circ}$ rotation |
| Input Impedance | $100 \mathrm{k} \Omega$ for 2 to 10 VDC ( 0.1 mA ), $500 \Omega$ for 4 to $20 \mathrm{~mA}, 1500 \Omega$ for PWM and on/off |
| Feedback Output U | 2 to 10 VDC |
| Angle of Rotation | Max. $95^{\circ}$, adjustable with mechanical stop |
| Torque motor | Min. 90 in-lbs [10 Nm] |
| Direction of Rotation (Motor) | reversible with built-in switch |
| Position Indication | reflective visual indicator (snap on) |
| Manual Override | external push button |
| Running Time (Motor) | 45 sec |
| Ambient Humidity | 5 to 95\% RH non condensing (EN 60730-1) |
| Ambient Temperature Range | $-22^{\circ} \mathrm{F}$ to $122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.50^{\circ} \mathrm{C}\right]$ |
| Storage Temperature Range | $-40^{\circ} \mathrm{F}$ to $176{ }^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $80^{\circ} \mathrm{C}$ ] |
| Housing | NEMA 2, IP54, UL Enclosure Type 2 |
| Housing Material | UL94-5VA |
| Agency Listings $\dagger$ | cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC and 2006/95/EC |
| Noise Level (Motor) | $<45 \mathrm{~dB}$ (A) |
| Servicing | maintenance free |
| Quality Standard | ISO 9001 |
| Weight | 2.2 lb [1 kg] |

$\dagger$ Rated Impulse Voltage 800V, Type action 1, Control Pollution Degree 3.

Torque min. $90 \mathrm{in}-\mathrm{lb}$, for control of damper surfaces up to 22 sq . ft .

## Application

For proportional modulation of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. The actuator is mounted directly to a damper shaft up to 1.05 " diameter by means of its universal clamp. A crank arm and several mounting brackets are available for applications where the actuator cannot be direct coupled to the damper shaft. The default parameters for 2 to 10 VDC applications of the ... MFT actuator are assigned during manufacturing. If necessary, custom versions of the actuators can be ordered. The parameters can be changed by two means: pre-set and custom configurations from Belimo or on-site configurations using the Belimo PC-Tool software.

## Operation

The actuator is not provided with and does not require any limit switches, but is electronically protected against overload. The anti-rotation strap supplied with the actuator will prevent lateral movement.

The NMCX series provides $95^{\circ}$ of rotation and a visual indicator indicates position of the actuator. When reaching the damper or actuator end position, the actuator automatically stops. The gears can be manually disengaged with a button on the actuator cover.

The NMCX24-MFT actuators use a brushless DC motor, which is controlled by an Application Specific Integrated Circuit (ASIC). The ASIC monitors and controls the actuator's rotation and provides a digital rotation sensing (DRS) function to prevent damage to the actuator in a stall condition. Power consumption is reduced in holding mode.

Add-on auxiliary switches or feedback potentiometers are easily fastened directly onto the actuator body for signaling and switching functions.

## Dimensions (Inches[mm])

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Ø1/2" to 1.05 [12.7 to 26.67]
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$\square$ 2/5" to 1.05 [10 to 26.67]


| Accessories |  |
| :---: | :---: |
| AV8-25 | 9.8" shaft extension for 5/16" to 1" diameter shafts. |
| ZG-NMSA-1 | Shaft extension for $1 / 2^{\prime \prime}$ diameter shafts ( $3.8{ }^{\prime \prime} \mathrm{L}$ ). |
| ZS-100 | Weather shield - galvaneal ( $13^{\prime \prime} \mathrm{L} \times 8^{\prime \prime} \mathrm{W} \times 6^{\prime \prime} \mathrm{D}$ ). |
| ZG-104 | Univ. right angle bracket ( $13-5 / 8^{\prime \prime} \mathrm{H} \times 7-1 / 2^{\prime \prime} \mathrm{W} \times 4$ " base). |
| ZG-NMA | AMB ( X ), $\mathrm{NMB}(\mathrm{X})$, $\mathrm{NKQB}(\mathrm{X})$ crankarm adaptor kit. |
| ZG-101 | Univ. right angle bracket ( $13^{\prime \prime} \mathrm{H} \times 11^{\prime \prime} \mathrm{W} \times 7-7 / 16^{\prime \prime}$ base). |
| ZG-103 | Univ. right angle bracket ( $7-1 / 2^{\prime \prime} \mathrm{H} \times 11^{\prime \prime} \mathrm{W} \times 2-3 / 4$ " base). |
| K-NA | Reversible NMB $(X)$ Clamp ( $1 / 2^{\prime \prime}$ to $3 / 4$ "). |
| ZG-100 | Univ. right angle bracket (17" H x 11-1/8" $\mathrm{W} \times 6$ " base). |
| TOOL-06 | 8 mm and 10 mm wrench. |
| ZS-150 | Weather shield - PC w/ foam seal ( 16 " L x 8-3/8" W x 4" D). |
| S2A | Auxiliary switch, 2x SPDT, 3A (0.5A inductive) @250 VAC max. |
| ZG-X40 | 120 to 24 VAC, 40 VA transformer. |
| ZG-R01 | 4 to 20 mA adaptor, $500 \Omega$, $1 / 4 \mathrm{~W}$ resistor $\mathrm{w} 6^{\prime \prime}$ pigtail wires. |
| NSV24 US | Battery back-up module for non-spring return actuators. |
| P2800A GR | Feedback potentiometer $2800 \Omega$. |
| P5000A GR | Feedback potentiometer $5000 \Omega$. |
| P500A GR | Feedback potentiometer $500 \Omega$. |
| SGA24 | Positioner control for modualting actuators (surface mount). |
| ADS-100 | Analog to digital switch for modulating actuators. |
| P370 | Shaft mount auxiliary switch, $1 / 2$ " shaft. |
| P10000A GR | Feedback potentiometer $10000 \Omega$. |
| P1000A GR | Feedback potentiometer $1000 \Omega$. |
| P140A GR | Feedback potentiometer $140 \Omega$. |
| S1A | Auxiliary switch, 1x SPDT, 3A (0.5A inductive) @250 VAC max. |

## Typical Specification

Modulating control damper actuators shall be electronic direct coupled type, which require no crank arm and linkage and be capable of direct mounting to a shaft up to 1.05 " diameter. Actuators must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a $500 \Omega$ resistor, a 4 to 20 mA control input from an electronic controller or positioner. Actuators shall have brushless DC motor technology and be protected from overload at all angles of rotation. Actuators shall have reversing switch and manual override on the cover. Run time shall be constant and independent of torque. Actuators shall be cULus listed, have a 5-year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

## Wiring Diagrams

Actuators with appliance cables are numbered.
Provide overload protection and disconnect as required.
Actuators may also be powered by 24 VDC.
Only connect common to negative (-) leg of control circuits.
A $500 \Omega$ resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.
Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 VAC line.
For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.
Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.

IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).


On/Off


Floating Point


VDC/mA Control


## PWM Contro



