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| See Page No． | 235 | 108 | 129 | 148 |  | 109 | 130 | 228 |  | 229 | 230 | 231 | 233 | 233 | 233 | 232 | 235 | 236 | 192 | 198 | 197 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 들 른 U 0 0 | Actuator Power Supply Simulator | Auxiliary Switch(es) |  |  |  | Feedback Potentiometer | Feedback Potentiometer | $\begin{aligned} & \frac{\infty}{0} \\ & \frac{0}{0} \\ & \frac{0}{\omega} \\ & 0 \\ & 0 \end{aligned}$ |  |  | Input Rescaling Module | Analog to Digital Switch |  | әр!^!व әбеఛ!ం^ \%0G |  | әןnpow dn－yoeg Kıəŋеg |  | Thermostat／Heater Kit |  | MFT Configuration Software |  |
|  | 으́ | $\begin{aligned} & N \\ & \text { N } \\ & \bar{\omega} \end{aligned}$ |  |  | $\begin{aligned} & \text { O} \\ & \mathbf{M} \\ & \mathbf{1} \end{aligned}$ | 0 | $\dot{\vdots}$ | N U U U N む U | $\begin{aligned} & \text { N } \\ & \text { た } \end{aligned}$ | $\begin{aligned} & \stackrel{\circ}{N} \\ & \stackrel{1}{⿺} \\ & \stackrel{1}{6} \end{aligned}$ |  | $\begin{aligned} & \text { 우́ } \\ & \text { فٌ } \end{aligned}$ | $\bar{\sim}$ $\stackrel{\rightharpoonup}{i}$ N | N O O N |  | $$ |  | $\begin{aligned} & \text { 똧 } \\ & \underset{N}{\text { N}} \end{aligned}$ |  |  |  |
| AF24（－S）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  | － | － |  |  |  |
| AF120（－S）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |
| AF230（－S）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |
| AF24－SR（－S）US | － |  |  |  | － |  |  | － |  | － |  | － | － | － |  |  | － | － |  |  |  |
| AF24－MFT（－S）US | － |  |  |  | － |  |  | － |  |  |  | － | － | － |  | － | － | － | － | － | － |
| AF24－MFT95 US | － |  |  |  | － |  |  |  |  |  |  |  |  |  | － |  | － | － | － | － | － |
| AF24－PC US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  | － | － |  |  |  |
| NF24（－S）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  | － | － |  |  |  |
| NF120（－S）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |
| NF24－SR（－S）US | － |  |  |  | － |  |  | － |  | － |  | － | － | － |  |  | － | － |  |  |  |
| NF24－MFT US | － |  |  |  | － |  |  | － |  |  |  | － | $\bigcirc$ | － |  | － | － | － | － | － | － |
| LF24（－S）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |  |
| LF120（－S）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| LF230（－S）US | － |  |  |  | $\bigcirc$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| LF（C）24－3．．．US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |  |
| LF24－SR．．．US | － |  |  |  | － |  |  | － |  | － | － | － | $\bigcirc$ | － |  |  | － |  |  |  |  |
| LF24－ECON．．．US | － |  |  |  | － |  |  | － |  |  |  |  |  |  |  |  | － |  |  |  |  |
| LF24－MFT．．．US | － |  |  |  | － |  |  | － | $\bigcirc$ |  |  | － | $\bigcirc$ | － |  | － | － |  | － | － | － |
| TF24（－S）US | － |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |  |
| TF120（－S）US | － |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| TF24－3（－S）US | － |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |  |
| TF24－SR（－S）US | － |  |  |  |  |  |  | － |  | － | － | － | － | － |  |  | － |  |  |  |  |
| GM24 US | － | － |  |  |  | － |  |  |  |  |  |  |  |  |  | － | － |  |  |  |  |
| GIM24－SR US | － | － |  |  |  | － |  | － |  | － | － | － | $\bigcirc$ | － |  | － | － |  |  |  |  |
| GM24－MFT US | － | － |  |  |  | － |  | － |  |  |  | － | $\bigcirc$ | － |  | － | － |  | － | － | － |
| AM24（－S）US | － |  | － |  | － |  | － |  |  |  |  |  |  |  |  | － | － |  |  |  |  |
| AM24－SR US | － |  | － |  | － |  | $\bigcirc$ | － |  | － | － | － | $\bigcirc$ | － |  | － | － |  |  |  |  |
| AM24－MFT US | － |  | － |  | － |  | － | － |  |  |  | － | － | － |  | － | － |  | － | － | － |
| AM24－MFT95 US | － |  | － |  | － |  | － |  |  |  |  |  |  |  | － |  | － |  | － | － | － |
| AM24－PC US | － |  | － |  | － |  | － |  |  |  |  |  |  |  |  |  | － |  |  |  |  |
| SM24－S US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |  |
| NM24 US | － |  |  | － | － |  |  |  |  |  |  |  |  |  |  | － | － |  |  |  |  |
| NM24－SR US | － |  |  | $\bigcirc$ | － |  |  | － |  | － | － | － | $\bigcirc$ | － |  | － | － |  |  |  |  |
| NM24－MFT US | － |  |  | － | － |  |  | － |  |  | － | － | $\bigcirc$ | － |  | － | － |  | － | － | － |
| NMQ24－MFT US | － |  |  | － | － |  |  | － |  |  |  | － |  |  |  |  | － |  | － | － | － |
| LM24－3（－5PO）（－T）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  | － | － |  |  |  |  |
| LM24（－S）（－10P）US | － |  |  |  | － |  |  |  |  |  |  |  |  |  |  |  | － |  |  |  |  |
| LM24－SR（－T）US | － |  |  |  | － |  |  | － |  | － | － | － | － | － |  | － | － |  |  |  |  |
| LMC24－SR US | － |  |  |  | － |  |  | － |  | － | － | － | $\bigcirc$ | － |  |  | － |  |  |  |  |
| LM24－MFT US | $\bigcirc$ |  |  |  | － |  |  | － |  |  |  | $\bigcirc$ | － | － |  | － | － |  | － | － | $\bigcirc$ |

For proportional actuators with a working range of 0 to 10 VDC or 2 to 10 VDC


Wiring diagram


| Technical Data | SGA24, SGF24 |
| :--- | :--- |
| Power supply | 24 VAC $\pm 20 \%$ 50/60 Hz 24 VDC $\pm 10 \%$ |
| Transformer sizing | 1 VA |
| Control signal Y | 0.5 to 10 VDC; 2 to 10 VDC (switchable) |
| Power output | up to 10 actuators (1 mA max) |
| Degree of protection | (SGA24 only NEMA 4 [1P54]) |
| Connection | Terminals (14 ga. wire max) |
| Humidity | 5 to $95 \%$ RH non-condensing |

## Application

These positioners are intended for the remote control of modulating actuators or for use as a minimum positioner (providing a minimum limit for the output signal from a modulating controller). The control range is 0 to $100 \%$ of the angle of rotation of the actuator.

Positioner SGA24 is for surface mounting with a NEMA 4 housing included. Positioner SGF24 is for flush mounting.

## Operation

The positioner receives its supply voltage through terminals 1 and 2. A rotary knob is turned, producing a proportional control signal ( Y ) at the output (terminal 3) of either 0.5 to 10 VDC or 2 to 10 VDC and therefore a proportional change in the position of the actuator between 0 and $100 \%$. When used for a minimum limit, the positioner works as a higher of 2 signal selector. This function allows only the signal from the controller or positioner, whichever is greater, to go to the actuator.

## Function

The changeover from 2 to 10 V to 0 to 10 V is selected by means of a slide switch on the printed circuit board.
The angle of rotation of the knob can be limited mechanically, by moving the adjustable stops under the knob.

## Accessory

ZG-SGF Mounting plate for single gang wiring box

Changeover switch


Drilling template for SGF24 (flush mount)


Dimensions [All numbers in brackets are in millimeters.]


# Pulse Width Modulation Interface PTA-250 

To convert a pulse width modulated signal to a 2 to 10 VDC signal for Belimo proportional actuators.
(Series 3)


Wiring diagram


| Technical Data | PTA-250 |
| :--- | :--- |
| Power supply | $24 \mathrm{VAC} \pm 15 \%$ |
|  | $24 \mathrm{VDC} \pm 15 \%$ | | Power consumption $<1 \mathrm{~W}$ |  |
| :--- | :--- |
| Transformer sizing | 2 VA |
| Input <br> isolation: | optically isolated (when wired as such) |
| type: | normal or triac, jumper selectable |
| trigger level: | 12 to 24 VAC/VDC or dry contact to com |
| time between <br> trigger pulses: | 12.5 milliseconds min |
| impedance: | VAC $-500 \Omega$, VDC $-10 \mathrm{~K} \Omega$ |
| pulse duration/ <br> resolution: | four selectable ranges, in seconds <br> of dry contact or SSR closure $\pm 40 \%$ <br> of signal increment |

Range 1: 0.0235 to 6 seconds/in 0.0235 sec increments
Range 2: 0.0196 to 5 seconds/in 0.0196 sec increments
Range 3: 0.1 to 25.5 seconds/in 0.100 sec increments
Range 4: 0.59 to 2.93 seconds/in in 0.0092 increments
\(\left.\begin{array}{lll}\hline Output \& - voltage: \& 2 to 10 VDC <br>
\& - current: \& 15 \mathrm{~mA} max <br>

\& - accuracy: \& \pm 2 \%\end{array}\right]\)|  | Electrical connection | wire terminals, 14 gauge max |
| :--- | :--- | :--- |
| Ambient temperature | $-20^{\circ} \mathrm{F}$ to $+150^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.+65^{\circ} \mathrm{C}\right]$ |  |
| Operating humidity | $5 \%$ to $95 \%$ non-condensing |  |
| Mounting | Snap-Track (provided) |  |
| Dimensions | - board: | $23 / 16^{\prime \prime} \times 23 / 16^{\prime \prime} \times 9 / 16^{\prime \prime}$ |
|  | - with Track: | $23 / 8^{\prime \prime} \times 21 / 4^{\prime \prime} \times 15 / 16^{\prime \prime}$ |
| Weight | 1.5 oz |  |

## Application

The PTA-250 converts a single pulse-width modulated input to an analog, 2 to 10 VDC, output to modulate a Belimo -SR actuator.
The PTA-250 is available for replacement of existing installations. The ...MFT product can replace $100 \%$ of the PTA-250 applications, more effectively.

## Operation

A timed contact or solid state closure from the controlling microprocessor controller is converted to a linear analog output with 256 steps of resolution. The last output is held until the PTA-250 receives the end of the next pulsed output. The PTA-250's output will not wrap around if an excessively long input pulse is received. Four input pulse clock rates are jumper selectable. Norma/Triac input positions are also jumper selectable. The input signal can be optically isolated from the PTA-250 circuit and can accept either positive or negative polarity. A red LED indicator is provided to indicate that power is applied to the PTA-250 and that the microprocessor is functioning. A green LED indicator is provided to indicate the presence of a pulse from the controller.
Note: The onboard zero and span adjustments are not for field use.


Control interface drawings


Dimensions [All numbers in brackets are in millimeters.]


To adjust the zero start point and working span of Belimo proportional ( . . -SR) actuators. (Series 3)


## Wiring diagram



| Technical Data | IRM-100 |
| :---: | :---: |
| Power supply | $\begin{array}{ll}\text { supply voltage: } & 24 \text { VAC } \pm 15 \% \\ & 24 \text { VDC } \pm 15 \%\end{array}$ |
| Power consumption | < 1 watt |
| Transformer sizing | 1 VA |
| Input voltage: | max voltage: 25 VDC <br> zero (starting point): 0 to 18 VDC <br> span adjustment: 2.6 to 17 VDC <br> impedance: $400 \mathrm{~K} \Omega$ <br> 0 to 20 mA <br> impedance: $500 \Omega$ |
| Output | voltage: 2 to 10 VDC <br> current: 15 mA max |
| Electrical connection wire terminals, 14 gauge max |  |
| Ambient temperature $-20^{\circ} \mathrm{F}$ to $+150^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.+65^{\circ} \mathrm{C}\right]$ |  |
| Humidity | 5 to 95\% RH non-condensing |
| Mounting | Snap-Track (provided) |
| Dimensions | board: $\quad 13 / 16^{\prime \prime} \times 23 / 16^{\prime \prime} \times 9 / 16^{\prime \prime}$ |
|  | w/Snap-Track: $17 / 8 " \times 2$ 3/8" x 15/16" |
| Weight | . 9 oz . |

## Application

The IRM-100 input rescaling module is designed to change nonstandard voltage or current signal levels into a 2 to 10 VDC output to modulate Belimo -SR type actuators. The IRM-100 is available for replacement of existing installations. The ...MFT product can replace $100 \%$ of the IRM-100 applications, more effectively.

## Operation

The IRM-100 is installed between a controller and a Belimo ...-SR actuator. The module can be adjusted to work with a zero offset of 0 to 18 VDC and a span range of 2.6 to 17 VDC. The IRM-100 has a 2 pin jumper mounted to the circuit board. When the jumper is connected between these 2 pins, a 4 to 20 mA signal can be fed directly into the IRM. The result being the conversion of a wide range of analog control signals to a 2 to 10 VDC range.


Jumper on both pins for 4 to 20 mA applications

The IRM may also be used to sequence several actuators from one signal source. This is done by adjusting the IRM units to work at different in put ranges.

IRM-100 used as a current amplifier
In some applications, the capacity of a controller output may not have current available to control multiple end devices. An example would be a controller which has an output current of .5 mA maximum. If 10 AF 24 -SR US actuators have to be driven from the same output, the current requirement would be $\mathrm{I}=\mathrm{E} / \mathrm{R}=(10$ volts $) /(100000 \Omega)=.1 \mathrm{~mA}$ for each actuator. For the 10 actuators, 1 mA of current would be necessary to properly control the actuators.

The IRM-100 may be used as an interface to provide a higher current capacity to the system. The IRM-100 has an output capacity of 15 mA . This higher level output can handle a greater number of actuators. By calibrating the IRM-100 for a 2 to 10 VDC input to achieve a 2 to 10 VDC output, IRM-100 provides this added capacity for the system.

The same circuit will also work if a 4 to 20 mA signal is used. A $500 \Omega$ resistor is placed across terminal \#1 and \#3 which converts the 4 to 20 mA to 2 to 10 VDC .

Dimensions [All numbers in brackets are in millimeters.]



## Wiring diagram



## Switchpoint adjustment drawings



## Application

To control reheat coils and/or a fan stage in a fan-powered terminal unit. The ADS-100 is controlled by a 2 to 10 VDC reheat output of a temperature controller. (TRS-M)

## Operation

The ADS-100 is designed to switch up to three independent stages of reheat on and off, according to a 2 to 10 VDC signal. The three output stages are furnished with a triac output. Each stage can be adjusted independently from each other over the 0 to $2.4^{\circ} \mathrm{F}$ throttling range of the TRS-M temperature controller.
The ADS-100 is shipped pre-adjusted, as shown in the following table. (Based on differential from setpoint)

|  | 1st. stage | 2nd. stage | 3rd. stage |
| :--- | :---: | :---: | :---: |
| Switch ON | $-0.45^{\circ} \mathrm{F}$ | $-1.35^{\circ} \mathrm{F}$ | $-2.25^{\circ} \mathrm{F}$ |
| Switch OFF | $-0.15^{\circ} \mathrm{F}$ | $-1.05^{\circ} \mathrm{F}$ | $-1.95^{\circ} \mathrm{F}$ |
| Switch ON | 2.8 V | 5.8 V | 8.8 V |
| Switch OFF | 0.4 V | 0.2 V | 0.4 V |

If desired, each stage may be field readjusted for special requirements. Three red LED indicators are provided to verify when the stages are energized.

## Setpoint readjustment

Tools required: small screwdriver, voltmeter.
To readjust the output stages, the following procedure is used: Connect the voltmeter to the desired switchpoint reference signal output and terminal 1 (COM). Readjust the switch point reference signal output with the corresponding potentiometer to your desired switch point. The adjustment range is 2.5 to 9.5 VDC . If you go below or above these values the ADS-100 may not switch off or on properly. If this occurs you have to increase or decrease your switching level until the ADS-100 works correctly.

## ADS-100 used as an auxiliary switch

The ADS-100 was originally designed as an accessory to switch on stages of electric reheat from an electronic thermostat. However, it can also function as an electronic auxiliary switch from any device which can provide 0 to 10 VDC signal, such as any feedback wire 5 from any ...SR or ...MFT type actuator.

The ADS-100 has 3 triac outputs rated at 10 VA maximum each which will turn on, in sequence, with an increasing voltage.

Dimensions [All numbers in brackets are in millimeters.]



Wiring diagram


| Technical Data | NSV24 |
| :---: | :---: |
| Power supply | $24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz}$ |
| Fusing | 4A slow blow fuse |
| Power consumption | Min. 5W (without actuator load) |
| Transformer | 8 VA |
| Batteries | 24 V Nominal 1.2 Ah (2-12 volt leadacid batteries; batteries not supplied with module) |
| Maintenance | The batteries should be checked annually (approximate life is 6 years) |
| Charging circuit | Charge current max. 150 mA Charge voltage 24-27 V, temperature compensated |
| Battery back-up operation | 24 V nominal 1.2 Ah, max. 60 W auto shut off after 250 seconds |
| Indication LED | Green - Main power source operation (battery will be charged) Red - Battery back-up operation |
| Mounting | Mounted in the control panel with an 11 terminal plug-in base (not supplied with module) |
| Ambient temperature | $14^{\circ} \mathrm{F}$ to $+122^{\circ} \mathrm{F}\left[-10^{\circ} \mathrm{C} \ldots+50^{\circ} \mathrm{C}\right]$ |

## Application

Several Belimo damper actuators can be used either with 24 VAC or 24 VDC.
In case of a power failure, the NSV24 battery back-up unit switches the damper actuator from its main AC power supply over to the 24 VDC battery to drive the actuators to their safety position.
For easy maintenance, the battery back-up system is placed in the control panel, not in the actuator.
Several actuators may be powered by one back-up module.
The batteries are separate from the
NSV24.

## Operation

The NSV24 is connected to the same
24 VAC power source as the damper actuators. It also charges the 24 V (2-12 volt batteries) storage battery. Its charge current is limited to 150 mA maximum, and the maximum charge voltage is temperature compensated.
In case of a power failure, the NSV24 switches immediately over to the battery power source, and according to the control function, the actuators will move to their safety position. After 250 seconds, the batteries are disconnected from the actuators to prolong battery life. Because of this, a safe battery back-up can be provided for several short-term failures. The main power source operation is indicated by a green LED, and the battery power source by a red LED.

Connectable Actuators

| Model | Maximum per module |
| :--- | :---: |
| GM24 US | 20 |
| GM24-MFT US | 15 |
| GM24-SR US | 15 |
| AM24 US | 30 |
| AM24-MFT US | 30 |
| AM24-SR US | 30 |
| NM24 US | 30 |
| NM24-MFT US | 30 |
| NM24-SR US | 30 |
| LM24-3 US | 30 |
| LM24-MFT US | 30 |
| LM24-SR-2.0 US | 30 |

## Accessories

NSV-BAT 12 VDC 1.2 Ah battery (2 required)

Dimensions [All numbers in brackets are in millimeters.]


NSV-BAT 12 V Battery


| Technical Data | NSV-BAT |
| :--- | :--- |
| Battery type | Lead-acid |
| Voltage | 12 VDC |
| Nominal capacity | 1.2 AH |
| Connections | .187 male spade |
| Weight | $1.32 \mathrm{lb}[.6 \mathrm{~kg}]$ |

## Application

The NSV-BAT battery is for use with the NSV24 battery backup module. It is a sealed, maintenance free, lead-acid battery. Two NSV-BAT batteries are required for one NSV24.

Dimensions [All numbers in brackets are in millimeters.]


## ZG-R01 Resistor for $\mathbf{4}$ to $\mathbf{2 0} \mathrm{mA}$ conversions



## Application

The ZG-R01 is a $499 \Omega$ Resistor which has been encased in a section of heat shrink tubing with short sections of hook up wire. The ZG-R01 is used to convert a 4 to 20 mA signal into a 2 to 10 VDC control signal.

Dimensions [All numbers in brackets are in millimeters.]


## ZG-R02 50\% voltage divider



## Application

The ZG-R02 is a voltage divider designed so that when connected to a $100 \mathrm{~K} \Omega$ input impedance, the output signal is $50 \%$ if the input signal. The voltage divider circuit is encased in a short section of heat shrink tubing with three short sections of hook up wire.

Dimensions [All numbers in brackets are in millimeters.]


## Resistor kits for multiple actuator applications



Resistor Kit No. ZG-R03


Resistor Kit No. ZG-R05


Resistor Kit No. ZG-R06

## Application

For use with the AF24-MFT95 US or AM24-MFT95 US actuators and Honeywell ${ }^{\circledR}$ controllers

ZG-R03 - see table to left
ZG-R05 - see table to left
ZG-R06 - see table to left


## ZG-CBNS Junction box

## Application

The ZG-CBNS accessory is used when the application requires the wiring terminations to be made at the actuator.

## Operation

The ZG-CBNS serves as an electrical junction box. The products that can be used with this accessory are as follows:

NF24 US, NF24-S US, NF120 US NF120-S US
NF24-SR US, NF24-MFT US
AF24 US, AF120 US, AF230 US
AF24-SR US, AF24-MFT US
Due to the internal volume of this junction box, according to UL requirements, The ZG-CBNS CANNOT be used with the following products:

NF24-S2 US
AF24-S US
AF120-S US
AF230-S US

| Technical Data | ZG-CBNS |
| :--- | :--- |
| Voltage rating | 250 VAC |
| Electrical connection | Maximum 5 line voltage connection |
| Housing rating | UL94 5V |
| Material type | $\mathrm{FR} / \mathrm{ABS} \mathrm{CYCOLAC} \mathrm{KJW4051}$ |
| Ambient temperature | $-22^{\circ} \mathrm{F}$ to $+122^{\circ} \mathrm{F}\left[-30^{\circ} \mathrm{C}\right.$ to $\left.+50^{\circ} \mathrm{C}\right]$ |
| Storage temperature | $-40^{\circ} \mathrm{F}$ to $+176^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right.$ to $\left.+80^{\circ} \mathrm{C}\right]$ |
| Agency listing | UL 873 (pending) |
| Quality standards | ISO 9001 |
| Weight | $<.5 \mathrm{lbs}$ |



Wiring diagram


| Technical Data | ZG-X40 |
| :--- | :--- |
| Primary Voltage | 120 VAC $50 / 60 \mathrm{~Hz}$ |
| Secondary Voltage | 24 VAC |
| Max VA Rating | 40 VA |
| Connections | $61 / 2^{\prime \prime}$ leads with stripped ends |
| Type | Class 2 |
| Mounting Method | $41 / 4$ " square outlet box cover |
| Agency Approvals | UL 1585, CSA 22.2 \#66 |

## Application

The ZG-X40 is a $40 \mathrm{VA}, 120$ to 24 VAC transformer. It is designed so that both the primary and secondary leads exit through the same side of a $41 / 4$ " square outlet box cover. With this design, all wiring can be done inside a standard Jbox with a minimum amount of labor.

Wire Specification

| No. 18 AWG leads, $61 / 2$ " length |  |
| :--- | :---: |
| Termination | Color |
| Primary | White-Black |
| Secondary | Yellow-Yellow |

## Maximum Number of Like Actuators per Transformer

| Model \# | Qty | Model \# | Qty |
| :--- | :---: | :--- | :---: |
| NM24 US | 11 | GM24-SR US | 5 |
| NM24-SR US | 13 | AF24. . US | 4 |
| AM24 US | 8 | NF24 (-S) US | 5 |
| SM24-S US | 3 | NF 120 (-S) US | 5 |
| AM24-SR US | 8 | NF24-SR US | 6 |
| AM24-MFT95 US | 8 | LF24 US | 8 |
| GM24 US | 6 | LF24-SR US | 8 |

Refers to appropriate actuator documentation for specific VA ratings.

# Power supply, signal simulator PS-100 



| Technical Data | PS-100 |
| :--- | :--- |
| Power supply | 120 VAC 50/60 Hz |
| Power consumption | < 4 W without actuator |
| Transformer | Primary: 120 VAC, 35 W <br> Secondary: 24 VAC, Class 2 trans. <br> PN: PS-XFMR |
| Terminal outputs | Push-button, wire terminals (12) <br> On-off, Floating Point <br> $135 \Omega, 0$ to 10 VDC |
| Input | 0 to 10 VDC |
| Display | LCD |
| Readouts, Output | 0 to 10 VDC in volts or percentage <br> based on a 2 to 10 VDC control span |
| Readouts, Input | 0 to 10 VDC in volts or percentage <br> based on a 2 to 10 VDC control span |
| Weight | 3 lbs [1.4 kg] with case |

## Application

The PS-100 power supply and signal simulator is designed to operate most proportional, floating, and on-off style actuators without the presence of a controller.
The PS-100 can produce 24 VAC on-off and floating control signal along with a 0 to 10 VDC and $135 \Omega$ proportional signal. A multi-function digital display is provided which can read either the 0 to 10 VDC output or a 0 to 10 VDC feedback signal either as voltage or percentage of control.
The PS-100 comes with a 120 to 24 VAC, plug into the wall transformer for power. Both the PS-100 and transformer are supplied in a black fabric carrying case.

Replacement Power Supply: PS-XFMR

Dimensions [All numbers in brackets are in millimeters.]



## Application

The ZG-HTR Thermostat/Heater kit is designed to be field installed to the NF and AF series actuators. The ZG-HTR provides a thermostatically controlled heater which allows the NF/AF actuators to be used below their normal low ambient temperature rating. At approximately $10^{\circ} \mathrm{F}\left[-12^{\circ} \mathrm{C}\right]$ the heater energizes to maintain the actuators internal temperature to within working limits. The rubberized heating element has an adhesive back which attaches to the side of the actuator housing. The thermostat assembly mounts to the rear of the actuator and provides for the connection of the 24 VAC supply voltage. The actuator/heater assembly should be contained in a housing, similar to the ZS-100 Weather Shield, to achieve best results.

Wiring diagram


Provide overload protection and disconnect as required.
The ZG-HTR may be wired to the same transformer as the actuator. Total VA ratings must be observed.

Power to the ZG-HTR must be applied continuously during the heating season. Do not wire the ZG-HTR to the on-off control signal when on-off type actuators are being used.

Dimensions [All numbers in brackets are in millimeters.]


| Technical Data | ZG-HTR |
| :--- | :--- |
| Power supply | $24 \mathrm{VAC} \pm 20 \% 50 / 60 \mathrm{~Hz}$ |
| Transformer sizing | 35 VA |
| Heater output | 35 watts |
| Actuator low ambient rating | with enclosure: $-40^{\circ} \mathrm{F}\left[-40^{\circ} \mathrm{C}\right]$ <br> enclosure with <br> $1^{\prime \prime}$ insulation: $\quad-58^{\circ} \mathrm{F}\left[-50^{\circ} \mathrm{C}\right]$ |
| Weight | 11 oz $[320 \mathrm{~g}]$ |

Special Control Range Applications

| Control Signal | Belimo Actuator | Accessory | Notes |
| :---: | :---: | :---: | :---: |
| 1 to 5 VDC | LM24-MFT US NM24-MFT US AM24-MFT US GM24-MFT US NF24-MFT US AF24-MFT US LF24-MFT US | None | Preset at factory or use MFT Handy device Set start point for 1 VDC, span for 4 VDC |
| 4 to 20 mA | Any -MFT,-SR Actuator | ZG-R01, or $500 \Omega$, 1/2 w resistor | Wire the ZG-R01 across the wires \#1 and \#3 |
| 10.5 to 13.5 VDC | LM24-MFT US NM24-MFT US AM24-MFT US AM24-MFT US GM24-MFT US NF24-MFT US AF24-MFT US LF24-MFT US | None | Preset at factory or use MFT Handy device Set start point for 10.5 VDC, span for 3 VDC |
| 14 to 17 VDC | LM24-MFT US NM24-MFT US AM24-MFT US SM24-MFT US GM24-MFT US NF24-MFT US AF24-MFT US LF24-MFT US | None | Preset at factory or use MFT Handy device Set start point for 14 VDC, span for 3 VDC |
| Pulse Width Modulation | LM24-MFT US NM24-MFT US AF24-MFT US AM24-MFT US SM24-MFT US NF24-MFT US AF24-MFT US LF24-MFT US | None | Preset at factory or use MFT Handy device |

*Preset at factory or use MFT Handy device
IRM-100 Calibrate the IRM-100 for an input range of 1 to 5 VDC. Calibrate IRM-100 2-10 in 2 to 10 out for signal amplification.
Sequencing Two or More Actuators With One Control Signal using the IRM-100


